# **INVARIANT CROSS-SECTIONS AND INVARIANT LINEAR SUBSPACES\***

#### **BY**

## KY FAN\*\*

#### **ABSTRACT**

Existence theorems for linear subspaces invariant under a continuous mapping and contained in a given set are obtained from a general theorem on existence ot invariant crosss-sections.

1. Introduction. For a continuous mapping  $\pi$  from a topological space X onto a topological space Y, a *cross-section* or a *n-cross-section* is, as usual, a continuous mapping  $\xi$  from Y into X such that  $\pi \circ \xi$  is the identity mapping on Y. Together with  $\pi$ , let a set  $\Gamma$  of  $\pi$ -cross-sections and a continuous mapping  $\phi$  from X into itself be given. We are interested in conditions which will ensure the existence of a  $\xi \in \Gamma$  invariant under  $\phi$ , i.e.,  $(\phi \circ \xi)(Y) \subset \xi(Y)$ . In §2 we give such an existence theorem. In the extreme case when Yconsists of a single point, a  $\pi$ -cross-section invariant under  $\phi$  is of course a fixed point of  $\phi$ . Thus Theorem 1 may be regarded as a new generalization of Tychonoff's fixed point theorem.

In  $\S$ 3 we consider a set X in a topological vector space E and a continuous linear transformation  $\phi$  from E into itself. We are interested in conditions which will ensure the existence of a linear subspace contained in  $X$  and invariant under  $\phi$ . Theorems 2 and 3 are results of this type. Less general results have been given in our earlier paper [3].

The results in §3 lend interesting geometric insight into certain known theorems on invariant linear subspaces with a special property for a particular class of linear transformations. As a first example, consider a linear transformation  $\phi$ from the *m*-dimensional real vector space  $R<sup>m</sup>$  into itself such that the matrix of  $\phi$  in some basis of  $R^m$  is totally positive, i.e., all minors of the matrix are positive. For a fixed positive integer  $n < m$ , let X denote the set of all those  $x \in \mathbb{R}^m$  such that the number of variations of sign in the coordinates (with respect to the chosen basis) of x is at most  $n-1$ . The total positivity implies the variation-diminishing property, so that  $\phi(X) \subset X$ . It is easy to see that there

Received March 18, 1964.

<sup>\*</sup> Lecture delivered at a symposium on Series and Geometry in Linear Spaces, held at the Hebrew University of Jerusalem from March 16 till March 24, 1964.

<sup>\*\*</sup> This work was supported in part by the National Science Foundation, Grant G-24865.

exists a  $(m - n)$ -dimensional linear subspace H in  $R<sup>m</sup>$  such that  $X \cap (x + H)$ is compact and convex for every  $x \in R^m$ . Therefore, according to Theorem 3 below, there exists an *n*-dimensional linear subspace L such that  $\phi(L) = L$  and the number of variations of sign in the coordinates of every point in Lis at most  $n-1$ . This is a well-known property, discovered by Gantmacher and Krein, of totally positive linear transformations (see [4]).

Another known result related to Theorem 3 is the following theorem of Pontriagin-Iohvidov-Krein [6, 8, 10]. Let  $E$  be the usual Hilbert space of infinite complex sequences  $x = \{x_i\}$  with  $\|\bar{x}\| = (\sum_{i=1}^{\infty} |x_i|^2)^{1/2} < \infty$ . Let *n* be a fixed positive integer and let  $q_n(x) = \sum_{i=1}^n |x_i|^2 - \sum_{i=n+1}^n |x_i|^2$  for  $x = \{x_i\} \in E$ . If  $\phi$  is a continuous linear transformation from E into itself, and if  $q_n(x) \ge 0$  implies  $q_p(x) \ge q_p(x)$ , then there exists an *n*-dimensional linear subspace L of E such that  $\phi(L) \subset L$  and  $g(x) \ge 0$  for  $x \in L$ . This theorem is fundamental in the study of spectral properties of linear transformations in a Hilbert space with an indefinite inner product (see  $[7, 9]$ ). A geometric reason for this theorem is again supplied by Theorem 3.

2. Existence of invariant cross-sections. For an arbitrary set  $F$  and a topological vector space E, we shall denote by  $E<sup>F</sup>$  the topological vector space of all functions from F into E, with the topology of pointwise convergence. Thus  $E^F$ may be identified with the product space  $\Pi_{\nu \in F} E_{\nu}$ , where each  $E_{\nu}$  is a copy of E. When E is separated and locally convex,  $E<sup>F</sup>$  is clearly also separated and locally convex.

THEOREM 1. *Let X be a set in a separated locally convex topological vector*  space E and Y a Hausdorff space. Let  $\pi$  be a continuous mapping from X onto Y, and  $\phi$  a continuous mapping from X into E. Let  $\Gamma$  be an equicontinuous set *of*  $\pi$ *-cross-sections such that*  $\Gamma$ , when regarded as in  $E^Y$ , is a nonempty compact *convex set in the topological vector space*  $E^Y$ . If for every  $\xi \in \Gamma$  there is an  $\eta \in \Gamma$ *such that*  $(\phi \circ \xi)(Y) \subset \eta(Y)$ , then there exists a  $\hat{\xi} \in \Gamma$  invariant under  $\phi$ , i.e.,  $(\phi \circ \hat{\xi})(Y) \subset \hat{\xi}(Y)$ .

**Proof.** Consider any  $\xi \in \Gamma$ . By hypothesis, there is an  $\eta \in \Gamma$  such that  $(\phi \circ \xi)(Y) \subset \eta(Y)$ . For each  $y \in Y$ , there is a  $z \in Y$  with  $(\phi \circ \xi)(y) = \eta(z)$ . Then since  $\pi \circ \eta$  is the identity mapping on Y, we have  $(\phi \circ \xi)(y) = \eta(z) = (\eta \circ \pi \circ \eta)(z)$  $=(\eta \circ \pi \circ \phi \circ \xi)(\nu)$ . Thus, for each  $\xi \in \Gamma$ , there is an  $\eta \in \Gamma$  such that

(1) 
$$
\phi \circ \xi = \eta \circ \pi \circ \phi \circ \xi.
$$

Let  $\xi_0 \in \Gamma$ , a finite set  $\{y_1, y_2, \dots, y_n\} \subset Y$  and a neighborhood U of 0 in E be given. We choose a neighborhood V of 0 in E such that  $\phi(x) - (\phi \circ \xi_0)(yi)$  $\in U(1 \leq i \leq n)$  holds for all  $x \in X$  satisfying  $x - \xi_0(y_i) \in V(1 \leq i \leq n)$ . Then  $\xi \in \Gamma$ and  $\xi(y_i) - \xi_0(y_i) \in V(1 \le i \le n)$  will imply  $(\phi \circ \xi)(y_i) - (\phi \circ \xi_0)(y_i) \in U (1 \le i \le n)$ . Hence the function  $\xi \to \phi \circ \xi$  from  $\Gamma$  into  $E^Y$  is continuous on  $\Gamma$ .

Next, let  $(\xi_0, \eta_0) \in \Gamma \times \Gamma$ , a finite set  $\{y_1, y_2, \dots, y_n\} \subset Y$  and a neighborhood U of 0 in E be given. By equicontinuity of  $\Gamma$ , there exists for each  $i = 1, 2, \dots, n$ , a neighborhood  $W_i$  of  $(\pi \circ \phi \circ \xi_0)(y_i)$  in Y such that

$$
\eta(y) - (\eta \circ \pi \circ \phi \circ \xi_0)(y_i) \in U
$$
 for  $y \in W_i$  and  $\eta \in \Gamma$ .

For this neighborhood  $W_i$  of  $(\pi \circ \phi \circ \xi_0)(y_i)$ , we find a neighborhood  $U_1$  of 0 in E such that for each  $i = 1, 2, \dots, n$ :

$$
(\pi \circ \phi \circ \xi)(y_i) \in W_i
$$
 for all  $\xi \in \Gamma$  satisfying  $\xi(y_i) \in \xi_0(y_i) + U_1$ .

Let  $N_1$  be the neighborhood of  $\xi_0$  in  $\Gamma$  formed by all  $\xi \in \Gamma$  satisfying

$$
\xi(y_i) - \xi_0(y_i) \in U_1 \qquad (1 \le i \le n).
$$

Let  $N_2$  be the neighborhood of  $\eta_0$  in  $\Gamma$  formed by all  $\eta \in \Gamma$  satisfying

$$
(\eta \circ \pi \circ \phi \circ \xi_0)(y_i) - (\eta_0 \circ \pi \circ \phi \circ \xi_0)(y_i) \in U \qquad (1 \leq i \leq n).
$$

Then we have

$$
(\eta \circ \pi \circ \phi \circ \xi)(y_i) - (\eta \circ \pi \circ \phi \circ \xi_0)(y_i) \in U \text{ for } \xi \in N_1, \ \eta \in \Gamma \text{ and } 1 \leq i \leq n,
$$

and therefore

 $(\eta \circ \pi \circ \phi \circ \zeta)(y_i) - (\eta_0 \circ \pi \circ \phi \circ \zeta_0)(y_i) \in U + U$  for  $\zeta \in N_1, \eta \in N_2$  and  $1 \leq i \leq n$ .

This proves that the function  $(\xi, \eta) \to \eta \circ \pi \circ \phi^0 \xi$  from  $\Gamma \times \Gamma$  into  $E^Y$  is continuous on  $\Gamma \times \Gamma$ .

Let  $\Delta$  denote the set of all  $(\xi,\eta) \in \Gamma \times \Gamma$  satisfying (1). For each  $\xi \in \Gamma$ , let  $\Delta(\xi) = {\eta \in \Gamma : (\xi, \eta) \in \Delta}$ . As we have seen at the beginning of the proof,  $\Delta(\xi)$ is nonempty for every  $\xi \in \Gamma$ . Since  $\Gamma$  is convex,  $\Delta(\xi)$  is convex. Since  $(\xi,\eta) \rightarrow \phi \circ \xi - \eta \circ \pi \circ \phi \circ \xi$  is a continuous function from  $\Gamma \times \Gamma$  into  $E^Y$ ,  $\Delta$  is closed in  $\Gamma \times \Gamma$ . Thus for every  $\xi \in \Gamma$ ,  $\Delta(\xi)$  is a nonempty closed convex subset of the compact convex set  $\Gamma$ .

The set-valued function  $\xi \to \Delta(\xi)$  is upper semi-continuous on  $\Gamma$  in the following sense: for any  $\xi_0 \in \Gamma$  and any open set G in  $E^Y$  such that  $\Delta(\xi_0) \subset G$ , there is a neighborhood  $N_0$  of  $\xi_0$  in  $\Gamma$  such that  $\Delta(\xi) \subset G$  for all  $\xi \in N_0$ . In fact, let  $\mathcal{N}$ be the family of all neighborhoods of  $\xi_0$  in  $\Gamma$ . If we denote  $\bigcup_{\xi \in N} \Delta(\xi)$  by  $\Delta(N)$ , then since  $\Delta$  is closed in  $\Gamma \times \Gamma$ , it is easy to see that  $\Delta(\xi_0) = \bigcap_{N \in \mathcal{N}} \overline{\Delta(N)}$ . If an open set G in  $E^Y$  contains  $\Delta(\xi_0)$ , then by compactness of  $\Gamma$ , there is a finite number of  $N_1, N_2, \cdots, N_k \in \mathcal{N}$  such that  $G = \bigcap_{i=1}^k \overline{\Delta(N_i)}$ . Then  $N_0 = \bigcap_{i=1}^k N_i \in \mathcal{N}$ and  $G = \Delta(N_0)$ .

We now apply a generalization  $\lceil 1, 5 \rceil$  of a fixed-point theorem of Kakutani. For the upper semi-continuous set-valued function  $\xi \to \Delta(\xi)$  defined on  $\Gamma$ , there exists a  $\hat{\zeta} \in \Gamma$  such that  $\hat{\zeta} \in \Delta(\hat{\zeta})$ . For this  $\hat{\zeta}$ , we have  $(\phi \circ \hat{\zeta})(Y) = (\hat{\zeta} \circ \pi \circ \phi \circ \hat{\zeta})(Y)$  $\subset \mathcal{E}(Y)$ , which completes the proof.

22 K. FAN [March]

Actually, Theorem 1 remains true, if the hypothesis on local convexity of the topological vector space  $E$  is replaced by the condition that every two distinct points of E may be separated by a continuous linear functional on  $E$ . This results from the following alternative proof.

**Another proof of Theorem** 1. As we have seen above, the proof of Theorem 1 amounts to showing the existence of a  $\hat{\xi} \in \Gamma$  satisfying

(2) 
$$
\phi \circ \xi = \xi \circ \pi \circ \phi \circ \xi.
$$

As in the first proof, we shall still need the facts that the function  $(\xi,\eta) \rightarrow \phi \circ \xi - \eta \circ \pi \circ \phi \circ \xi$  from  $\Gamma \times \Gamma$  into  $E^Y$  is continuous on  $\Gamma \times \Gamma$ , and that for each  $\xi \in \Gamma$  there is an  $\eta \in \Gamma$  satisfying (1).

Instead of local convexity, we assume now that any two distinct points of  $E$ can be separated by a continuous linear functional on  $E$ . It follows that  $E<sup>r</sup>$ also has this property. For a continuous linear functional f on  $E^Y$ , let  $\Phi(f)$  denote the set of all  $\xi \in \Gamma$  satisfying  $f(\phi \circ \xi - \xi \circ \pi \circ \phi \circ \xi) = 0$ . The existence of a  $\xi$ satisfying (2) means  $\bigcap_i \Phi(f) \neq \emptyset$ , where the intersection is taken over all continuous linear functionals f on E<sup>r</sup>. Since  $\Phi(f)$  is a closed subset of the compact set  $\Gamma$ , it suffices to prove that  $\bigcap_{i=1}^{n} \Phi(f_i) \neq \emptyset$  for any finite number of continuous linear functionals  $f_i$  on  $E^Y$ .

Given any finite set  $\{f_1, f_2, \dots, f_n\}$  of continuous linear functionals on  $E^Y$ , consider the set  $\Psi$  formed by all  $(\xi, \eta) \in \Gamma \times \Gamma$  satisfying

$$
\sum_{i=1}^n |f_i(\phi \circ \xi - \xi \circ \pi \circ \phi \circ \xi)| \leq \sum_{i=1}^n |f_i(\phi \circ \xi - \eta \circ \pi \circ \phi \circ \xi)|.
$$

We observe that: (i)  $\Gamma$  is a nonempty compact convex set in  $E^Y$  and  $\Psi$  is a closed subset of  $\Gamma \times \Gamma$ ; (ii)  $(\xi, \xi) \in \Psi$  for each  $\xi \in \Gamma$ ; (iii) for each  $\xi \in \Gamma$ , the set  ${n \in \Gamma : (\xi, \eta) \notin \Psi}$  is convex (or empty). These facts (i)-(iii) imply [2, Lemma 4] the existence of a  $\xi_1 \in \Gamma$  such that  $(\xi_1, \eta) \in \Psi$  for all  $\eta \in \Gamma$ ; this implication does not require local convexity of  $E^Y$ . For this  $\xi_1$ , we can find an  $\eta_1 \in \Gamma$  such that  $\phi \circ \xi_1 = \eta_1 \circ \pi \circ \phi \circ \xi_1$ , which together with  $(\xi_1, \eta_1) \in \Psi$  imply that  $f_i(\phi \circ \xi_1 - \xi_1 \circ \pi \circ \phi \circ \xi_1) = 0$  for  $1 \leq i \leq n$ . Thus  $\xi_1 \in \bigcap_{i=1}^n \Phi(f_i) \neq \emptyset$ , which was to be proved.

COROLLARY 1. Let X be a set in a separated locally convex topologicalvector *space E. Let lr be a continuous mapping from X onto a Hausdorff space Y such that the following conditions are fulfilled:* 

(3) For each  $y \in Y$ ,  $\pi^{-1}(y)$  is compact and convex.

(4) *The set*  $\Gamma_0$  *of all*  $\pi$ *-cross-sections is nonempty and equicontinuous on Y.* Let  $\phi$  be a continuous mapping from X into E. If for every  $\xi \in \Gamma_0$  there is *an*  $\eta \in \Gamma_0$  *such that*  $(\phi \circ \xi)(Y) \subset \eta(Y)$ , *then there exists a*  $\xi \in \Gamma_0$  *such that*  $(\phi \circ \hat{\xi})(Y) \subset \hat{\xi}(Y).$ 

**Proof.** By Theorem 1, it suffices to verify that the set  $\Gamma_0$  of all  $\pi$ -cross-sections is a convex compact set in  $E<sup>Y</sup>$ .

Let  $\xi_1, \xi_2 \in \Gamma_0$  and let  $\xi = c_1\xi_1 + c_2\xi_2$ , where  $c_1 \ge 0$ ,  $c_2 \ge 0$  and  $c_1 + c_2 = 1$ . For each  $y \in Y$ ,  $\xi_1(y)$  and  $\xi_2(y)$  are in the convex set  $\pi^{-1}(y)$ , so  $\xi(y) \in \pi^{-1}(y)$ . Hence  $\xi(Y) \subset X$  and  $\pi \circ \xi$  is the identity mapping on Y. As  $\xi$  is clearly continuous, we have  $\xi \in \Gamma_0$ . Thus  $\Gamma_0$  is convex.

For each  $y \in Y$ ,  $\{\xi(y): \xi \in \Gamma_0\}$  is contained in the compact set  $\pi^{-1}(y)$ . It follows that  $\Gamma_0$  is relatively compact in  $E^Y$ . It remains to verify that  $\Gamma_0$  is closed in  $E^Y$ . Let  $\zeta_0$  be in the closure of  $\Gamma_0$  in  $E^Y$ . For each  $y \in Y$ ,  $\zeta(y)$  is in the compact set  $\pi^{-1}(y)$  for every  $\xi \in \Gamma_0$ ; so we must have  $\xi_0(y) \in \pi^{-1}(y)$ . Thus  $\xi_0(Y) \subset X$  and  $\pi \circ \xi_0$  is the identity mapping on Y. That  $\xi_0$  is continuous on Y follows from the equicontinuity of  $\Gamma_0$  and the fact that  $\xi_0$  is in the closure of  $\Gamma_0$ . Hence  $\xi_0 \in \Gamma_0$ . This verifies that  $\Gamma_0$  is closed in  $E^Y$  and therefore is compact.

3. Existence **of invariant linear subspaces.** In this section we apply Theorem 1 to study invariant linear subspaces contained in a given set.

THEOREM 2. *Let E, F be two separated locally convex topological vector spaces, and let p be a continuous linear transformation from E onto F. Let X be a set in E having the following properties:* 

(5) For each  $y \in F$ ,  $\rho^{-1}(y) \cap X$  is compact and convex.

(6) *There is a neighborhood W of 0 in F such that*  $\rho^{-1}(W) \cap X$  *is bounded.* 

(7) *X contains a linear subspace L (not necessarily closed) of E such that*   $\rho(L) = F$ .

Let  $\Lambda$  denote the family of all linear subspaces L of E such that  $L \subset X$  and  $\rho(L) = F$ . If  $\phi$  is a continuous mapping from X into E such that for every  $L \in \Lambda$ ,  $\phi(L)$  is contained in some  $M \in \Lambda$ , then there exists an  $\hat{L} \in \Lambda$  with  $\phi(\hat{L}) \subset \hat{L}$ .

**Proof.** Let  $\Gamma$  denote the set of all  $\xi \in E^F$  such that  $\xi(F) \subset X$ ,  $\xi$  is linear and  $\rho \circ \xi$  is the identity mapping on F. Then  $\xi(F) \in \Lambda$  for every  $\xi \in \Gamma$ . By(5),  $X \cap \text{Ker } \rho$ is compact, so  $L \cap \text{Ker } \rho = \{0\}$  for every  $L \in \Lambda$ . Thus to each  $L \in \Lambda$  there corresponds a unique  $\zeta \in \Gamma$  with  $\zeta(F) = L$ . Hence  $\Lambda = {\zeta(F) : \zeta \in \Gamma}$ , and (7) means that  $\Gamma$  is nonempty.

Consider an arbitrary neighborhood U of 0 in E. By (6),  $\rho^{-1}(W) \cap X$  is bounded, so there is an  $r > 0$  such that  $\rho^{-1}$  (W)  $\cap X \subset rU$ . Then for every  $\xi \in \Gamma$ we have  $\zeta(W) \subset \rho^{-1}(W) \cap X \subset rU$  or  $\zeta(r^{-1}W) \subset U$ . As W is a neighborhood of 0 in  $F$ , this shows that the set  $\Gamma$  of linear transformations is equicontinuous.

Let  $\xi_1,\xi_2 \in \Gamma$  and  $\xi = c_1\xi_1 + c_2\xi_2$ , where  $c_1 \ge 0$ ,  $c_2 \ge 0$ ,  $c_1 + c_2 = 1$ . Then for each  $y \in F$ , the points  $\xi_1(y)$  and  $\xi_2(y)$  are in the convex set  $\rho^{-1}(y) \cap X$ , so  $\xi(y) \in \rho^{-1}(y) \cap X$ . Hence  $\xi(F) \subset X$  and  $\rho \circ \xi$  is the identity mapping on *F*. As  $\xi$  is linear, we have  $\xi \in \Gamma$ . Thus  $\Gamma$  is a convex set in  $E^F$ .

Let  $\xi_0$  be in the closure of  $\Gamma$  in  $E^F$ . Then  $\xi_0$  is necessarily linear. For each  $y \in F$ ,  $\xi(y)$  is contained in the compact set  $\rho^{-1}(y) \cap X$  for every  $\xi \in \Gamma$ . This implies  $\xi_0(y) \in \rho^{-1}(y) \cap X$ . Hence  $\xi_0(F) \subset X$  and  $\rho \circ \xi_0$  is the identity mapping on F, i.e.,  $\xi_0 \in \Gamma$ . This shows that  $\Gamma$  is closed in  $E^F$ . For each  $y \in F$ ,  $\{\xi(y): \xi \in \Gamma\}$  being contained in the compact set  $p^{-1}(y) \cap X$ , is relatively compact in E. It follows that  $\Gamma$  is relatively compact in  $E^F$  and therefore is compact.

If we denote by  $\pi$  the restriction of  $\rho$  on X, then  $\pi(X) = F$ .  $\Gamma$  is an equicontinuous set of  $\pi$ -cross-sections and it is a nonempty compact convex set in  $E^F$ .

Let  $\xi \in \Gamma$  and  $L = \xi(F)$ . Then  $L \in \Lambda$ , so there is an  $M \in \Lambda$  such that  $\phi(L) \subset M$ . Let  $\eta \in \Gamma$  be such that  $M = \eta(F)$ . Then  $(\phi \circ \xi)(F) = \phi(L) \subset \eta(F)$ . By Theorem 1, there exists a  $\hat{\zeta} \in \Gamma$  such that  $(\phi \circ \hat{\zeta})(F) \subset \hat{\zeta}(F)$ . Then  $\hat{L} = \hat{\zeta}(F) \in \Lambda$  and  $\phi(\hat{L}) \subset \hat{L}$ , and the theorem is proved.

COROLLARY 2. Let a normed vector space E be the direct sum  $E = E_1 \oplus E_2$ *of two closed linear subspaces*  $E_1$ ,  $E_2$ , *of which*  $E_2$  *is reflexive. For*  $x = y + z$ *with*  $y \in E_1$ ,  $z \in E_2$ , let  $q(x) = ||y|| - ||z||$ . Let  $\Lambda$  be the family of all those *linear subspaces (not necessarily closed) L of E such that*  $\pi(L) = E_1$  and  $q(x) \ge 0$  for  $x \in L$ , where  $\pi$  denotes the projection from  $E_1 \oplus E_2$  onto  $E_1$ . Let  $\phi$  be a continuous linear transformation from E into itself. If, for any L $\epsilon \Lambda$ , *there is an*  $M \in \Lambda$  *with*  $\phi(L) \subset M$ , then there exists an  $\hat{L} \in \Lambda$  with  $\phi(\hat{L}) \subset \hat{L}$ .

**Proof.** We use the weak topology of E, for which both  $\pi$  and  $\phi$  remain continuous. Let  $X = \{x \in E : q(x) \ge 0\}$ . For each  $y \in E_1$ ,  $\pi^{-1}(y) \cap X = \{y + z:$  $z \in E_2$  and  $||z|| \le ||y||$  is clearly convex; it is weakly compact since  $E_2$  is reflexive. If  $W = \{y \in E_1 : ||y|| \le 1\}$ , then  $\pi^{-1}(W) \cap X = \{y + z : y \in E_1, z \in E_2 \text{ and } z \in E_1\}$  $||z|| \le ||y|| \le 1$  is bounded. Thus the result follows from Theorem 2.

THEOREM 3. *Let E be a separated locally convex topological vector space. Let n be a positive integer and X a set in E having the following properties:* 

(8) *There exists a closed linear subspace H in E of codimension n such that*   $X \cap (x + H)$  is compact and convex for every  $x \in E$ .

(9) *X contains an n-dimensional linear subspace of E.* 

Let  $\phi$  be a continuous linear transformation from E into itself such that:  $(10)$   $\phi(X) \subset X$ .

(11) *No* 1-dimensional linear subspace of E is contained in  $X \cap \text{Ker}\phi$ . *Then there exists an n-dimensional linear subspace L of E such that*  $L \subset X$ *and*  $\phi(L) = L$ .

Proof. Observe first that in case F is finite dimensional, Theorem 2 **remains**  valid without hypothesis (6). In the proof of Theorem 2, hypothesis (6) was used only in establishing the equicontinuity of  $\Gamma$ . (For the notation, see Theorem 2 and its proof.) In case F is of finite dimension n, the equicontinuity of  $\Gamma$  is a consequence of (5). In fact, let  $\{e_1, e_2, \dots, e_n\}$  be a basis of F, and let U be an arbitrary balanced convex neighborhood of 0 in E. Since  $\rho^{-1}(e_i) \cap X$  is compact, there is an  $r > 0$  such that  $r(\rho^{-1}(e_i) \cap X) \subset U$  for  $1 \le i \le n$ . Then  $\xi(e_i) \in r^{-1}U$ for all  $\xi \in \Gamma$  and  $1 \leq i \leq n$ . As U is balanced and convex, we have  $\xi(y) = \sum_{i=1}^n c_i \xi(e_i) \in U$  for all  $\xi \in \Gamma$  and all  $y = \sum_{i=1}^n c_i e_i$  satisfying  $\sum_{i=1}^n |c_i| \leq r$ . Thus  $\Gamma$  is equicontinuous.

Now under the hypothesis of the present theorem, let  $\rho$  denote the canonical mapping from E onto  $E/H$ , and let  $F = E/H$ . Then dim  $F = n$ . Let  $\Lambda$  denote the family of all *n*-dimensional linear subspaces of E contained in  $X$ . By (10) and (11), we have  $\phi(L) \subset X$  and dim  $\phi(L) = n$  for  $L \in \Lambda$ . Thus  $\phi(L) \in \Lambda$ for LeA. By (8),  $X \cap \text{Ker } \rho = X \cap H$  is compact, so  $L \cap \text{Ker } \rho = \{0\}$  for  $L \in \Lambda$ . Hence  $\Lambda$  is precisely the family of all linear subspaces L of E such that  $L \subset X$ and  $\rho(L) = F$ . All hypotheses except (6) of Theorem 2 are satisfied. Since F is finite dimensional, the present theorem follows.

The following corollary has been given in [3]. It follows from Theorem 3 in the same manner that Corollary 2 follows from Theorem 2.

**COROLLARY 3.** Let a Banach space E be the direct sum  $E = E_1 \oplus E_2$  of two *linear subspaces, of which*  $E_1$  *is of finite dimension n and*  $E_2$  *is reflexive. For*  $x = y + z$  with  $y \in E_1$ ,  $z \in E_2$ , let  $q(x) = ||y|| - ||z||$ . Let  $\phi$  be a continuous *linear transformation from E into itself. If*  $x \neq 0$  *and*  $q(x) \geq 0$  *imply*  $\phi(x) \neq 0$ *and*  $q(\phi(x)) \ge 0$ *, then there exists an n-dimensional linear subspace L of E such that*  $\phi(L) = L$  *and*  $q(x) \ge 0$  *for all*  $x \in L$ .

#### **REFERENCES**

1. Fan, K., 1952, Fixed-point and minimax theorems in locally convex topological linear spaces, *Proe. Nat. Aead. Sei. U.S.A.,* 38, 121-126.

2. Fan, K., 1961, A generalization of Tychonoff's fixed point theorem, *Math. Annalen,* 142, 305-310.

3. Fan, K., 1963,Invariant subspaces of certain linear *operators, Bull. Amer. Math. Soe.,* 69, 773-777.

4. Gantmacher, F.R. and Krein, M.G., 1960, *Oszillationsmatrizen, Oszillationskerne grid kleine Sehwingungen meehanischer Systeme,* Akademie Verlag, Berlin.

5. Glicksberg, I.L., 1952, A further generalization of the Kakutani fixed point theorem, with application to Nash equilibrium points, *Proc. Amer. Math. Soc.*, 3, 170–174.

6. Iohvidov, I.S., 1949, Unitary operators in a space with indefinite metric, *Zapiski Har'kov. Mat. Obšč.*, 21 (4), 79-86 (Russian).

7. Iohvidov, I.S. and Krein, M.G., 1956, Spectral theory of operators in spaces with an indefinite metric I, *Trudy Moskov. Mat. Obšč.*, 5, 367-432 (Russian); English transl., Amer. *Math. \$oe. Transl. Set.* 2, 13 (1960), 105-175.

### 26 K. FAN

8. Krein, M.G., 1950, On an application of the fixed-point principle in the theory of linear transformations of spaces with an indefinite metric, *Uspehi Mat. Nauk.,5,* No. 2 (36), 180-190 (Russian) ;English tansl., *Amer. Math. Soc. Transl. Ser.* 2, 1 (1955), 27-35.

9. Naimark, M.A., 1963, Commutative unitary operators on a  $\pi_k$  space, *Doklady Akad. Nauk SSSR.,* 149, 1261-1263 (Russian); English transl., *Soviet Math.,* 4 (1963), 543-545.

10. Pontrjagin, L.S., 1944, Hermitian operators in spaces with indefinite metric, *Izvestiya Akad. Nauk SSSR. Set. Mat.,* 8, 243-280 (Russian, English summary).

NORTHWESTERN UNIVERSITY EVANSTON, ILLINOIS